

Adaptive Security of Constrained PRFs

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Abstract. Constrained pseudorandom functions have recently been introduced independently by Boneh and Waters (Asiacrypt’13), Kiayias et al. (CCS’13), and Boyle et al. (PKC’14). In a standard pseudorandom function (PRF) a key k is used to evaluate the PRF on all inputs in the domain. Constrained PRFs additionally offer the functionality to delegate “constrained” keys k_S which allow to evaluate the PRF only on a subset S of the domain.

The three above-mentioned papers all show that the classical GGM construction (J.ACM’86) of a PRF from a pseudorandom generator (PRG) directly yields a constrained PRF where one can compute constrained keys to evaluate the PRF on all inputs with a given prefix. This constrained PRF has already found many interesting applications. Unfortunately, the existing security proofs only show selective security (by a reduction to the security of the underlying PRG). To achieve full security, one has to use complexity leveraging, which loses an exponential factor 2^N in security, where N is the input length.

The first contribution of this paper is a new reduction that only loses a quasipolynomial factor $q^{\log N}$, where q is the number of adversarial queries. For this we develop a new proof technique which constructs a distinguisher by interleaving simple guessing steps and hybrid arguments a small number of times. This approach might be of interest also in other contexts where currently the only technique to achieve full security is complexity leveraging.

Our second contribution is concerned with another constrained PRF, due to Boneh and Waters, which allows for constrained keys for the more general class of bit-fixing functions. Their security proof also suffers from a 2^N loss, which we show is inherent. We construct a meta-reduction which shows that any “simple” reduction of full security from a non-interactive hardness assumption must incur an exponential security loss.

Keywords: Constrained pseudorandom functions, full security, complexity leveraging, meta-reduction.

1 Introduction

PRFs. Pseudorandom functions (PRFs) were introduced by Goldreich, Goldwasser and Micali [GGM86]. A PRF is an efficiently computable keyed function

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$F: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y}$, where $F(K, \cdot)$, instantiated with a random key $K \leftarrow^* \mathcal{K}$, cannot be distinguished from a function randomly chosen from the set of all functions $\mathcal{X} \rightarrow \mathcal{Y}$ with non-negligible probability.

Constrained PRFs. The notion of constrained PRFs (CPRFs) was introduced independently by Boneh and Waters [BW13], Boyle, Goldwasser and Ivan [BGI14] and Kiayias, Papadopoulos, Triandopoulos and Zacharias [KPTZ13].⁴

A constrained PRF is defined with respect to a set system $\mathcal{S} \subseteq 2^{\mathcal{X}}$ and supports the functionality to “delegate” (short) keys that can only be used to evaluate the function $F: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y}$ on inputs specified by a subset $S \in \mathcal{S}$. Concretely, there is a “constrained” keyspace \mathcal{K}_c and additional algorithms $F.\text{constrain}: \mathcal{K} \times \mathcal{S} \rightarrow \mathcal{K}_c$ and $F.\text{eval}: \mathcal{K}_c \times \mathcal{X} \rightarrow \mathcal{Y}$, which for all $k \in \mathcal{K}, S \in \mathcal{S}, x \in S$ and $k_S \leftarrow F.\text{constrain}(k, S)$, satisfy $F.\text{eval}(k_S, x) = F(k, x)$ if $x \in S$ and $F.\text{eval}(k_S, x) = \perp$ otherwise.

The GGM and the Boneh-Waters construction. All the aforementioned papers [BW13,BGI14,KPTZ13] show that the classical GGM [GGM86] construction of the PRF $\text{GGM}: \{0, 1\}^\lambda \times \{0, 1\}^N \rightarrow \{0, 1\}^\lambda$ from a length-doubling pseudorandom generator (PRG) $G: \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda}$ directly gives a constrained PRF, where for any key K and input prefix $z \in \{0, 1\}^{\leq N}$, one can generate a constrained key K_z that allows to evaluate $\text{GGM}(K, x)$ for any x with prefix z . This simple constrained PRF has found many applications; apart from those discussed in [BW13,BGI14,KPTZ13], it can be used to construct so-called “punctured” PRFs, which are a key ingredient in almost all the recent proofs of indistinguishability obfuscation [SW14,BCPR13,HSW14].

Boneh and Waters [BW13] construct a constrained PRF for a much more general set of constraints, where one can delegate keys that fix any subset of bits of the input (not just the prefix, as in GGM). The construction is based on leveled multilinear maps [GGH13] and its security is proven under a generalization of the decisional Diffie-Hellman assumption.

Security of constrained PRFs. The security definition for normal PRFs is quite intuitive. One considers two experiments: the “real” experiment and the “random” experiment, in both of which an adversary A gets access to an oracle $\mathcal{O}(\cdot)$ and then outputs a bit. In the real experiment $\mathcal{O}(\cdot)$ implements the PRF $F(K, \cdot)$ using a random key; in the random experiment $\mathcal{O}(\cdot)$ implements a random function. The PRF is secure if every efficient A outputs 1 in both experiments with (almost) the same probability.

Defining the security of constrained PRFs requires a bit more thought. We want to give an adversary access not only to $F(K, \cdot)$, but also to the constraining function $F.\text{constrain}(K, \cdot)$. But now we cannot expect the values $F(K, \cdot)$ to look random, as an adversary can always ask for a key $K_S \leftarrow F.\text{constrain}(K, S)$ and then for any $x \in S$ check whether $F(K, x) = F.\text{eval}(K_S, x)$.

⁴ The name “constrained PRF” is from [BW13]; in [KPTZ13] and [BGI14] these objects are called “delegatable PRFs” and “functional PRFs”, respectively. In this paper we follow the naming and notation from [BW13].

Instead, security is formalized by defining the experiments in two phases. In the first phase of both experiments the adversary gets access to the same oracles $F(K, \cdot)$ and $F.\text{constrain}(K, \cdot)$. The experiments differ in a second phase, where the adversary chooses some challenge query x^* . In the real experiment the adversary then obtains $F(K, x^*)$, whereas in the random experiment she gets a random value. Intuitively, when no efficient adversary can distinguish these two games, this means that the outputs of $F(K, \cdot)$ look random on all points that the adversary cannot compute by herself using the constrained keys she has received so far.

Selective vs. full security. In the above definition we let the adversary choose the challenge input x^* after she gets access to the oracles. This is the notion typically considered, and it is called “full security” or “adaptive security”. One can also consider a weaker “selective security” notion, where the adversary must choose x^* before getting access to the oracles.

The reason to consider selective security notions, not only here, but also for other objects like identity-based encryption [BF01, BB04, AFL12] is that it is often much easier to achieve. Although there exists a simple generic technique called “complexity leveraging”, which translates any selective security guarantee into a security bound for full security, this technique (which really just consists of guessing the challenge) typically loses an exponential factor (in the length of the challenge) in the quality of the reduction, often making the resulting security guarantee meaningless for practical parameters.

1.1 Our Contributions

All prior works [BW13, BGI14, KPTZ13] only show selective security of the GGM constrained PRF, and [BW13] also only give a selective-security proof for their bit-fixing constrained PRF. In this paper we investigate the full security of these two constructions. For GGM we achieve a positive result, giving a reduction that only loses a quasipolynomial factor. For the Boneh-Waters bit-fixing CPRF we give a negative result, showing that for a large class of reductions, an exponential loss is necessary. We now elaborate on these results.

A quasipolynomial reduction for GGM. To prove full security of GGM: $\{0, 1\}^\lambda \times \{0, 1\}^N \rightarrow \{0, 1\}^\lambda$, the “standard” proof proceeds in two steps (we give a precise statement in Proposition 2).

1. A guessing step (a.k.a. complexity leveraging), which reduces full to selective security. This step loses an exponential factor 2^N in the input length N .
2. Now one applies a hybrid argument which loses a factor $2N$.

The above two steps transform an adversary A_f that breaks the full security of GGM with advantage ϵ into a new adversary that breaks the security of the underlying pseudorandom generator G (used to construct the GGM function) with advantage $\epsilon/(2N \cdot 2^N)$. As a consequence, even if one makes a strong exponential hardness assumption on the PRG G , one must use a PRG whose domain is $\Theta(N)$ bits in order to get any meaningful security guarantee.

The reason for the huge security loss is the first step, in which one guesses the challenge $x^* \in \{0,1\}^N$ the adversary will choose, which is correct with probability 2^{-N} . To avoid this exponential loss, one must avoid guessing the entire x^* . Our new proof also consists of a guessing step followed by a hybrid argument.

1. A guessing step, where (for some ℓ) we guess which of the adversary’s queries will be the *first* one that agrees with x^* in the first ℓ positions.⁵ This step loses a factor q , which denotes the number of queries made by the adversary.
2. A hybrid argument which loses a constant factor 3.

The above two steps only lose a factor $3q$. Unfortunately, after one iteration of this approach we do not get a distinguisher for G right away. At a high level, these two steps achieve the following: We start with two games which in some sense are at distance N from each other, and we end up with two games which are at distance $N/2$. We can iterate the above process $n := \log N$ times to end up with games at distance $N/2^n = 1$. Finally, from any distinguisher for games at distance 1 we can get a distinguisher for the PRG G with the same advantage. Thus, starting from an adversary against the full security of GGM with advantage ϵ , we get a distinguisher for the PRG with advantage $\epsilon/(3q)^{\log N}$.

We can optimize this by combining this approach with the original proof, and thereby obtain a quasipolynomial loss of $2q \log q \cdot (3q)^{\log N - \log \log q}$. To give some numerical example, let the input length be $N = 2^{10} = 1024$ and the number of queries be $q = 2^{32}$. Then we get a loss of $2q \log q \cdot (3q)^{\log N - \log \log q} = 2 \cdot 2^{32} \cdot 32 \cdot (3 \cdot 2^{32})^{10-5} = 2^{198} \cdot 3^5 \leq 2^{206}$, whereas complexity leveraging loses $2N2^N = 2^{1035}$.

Although our proof is somewhat tailored to the GGM construction, the general “fine-grained” guessing approach outlined above might be useful to improve the bounds for other constructions (like CPRFs, and even IBE schemes) where currently the only proof technique that can be applied is complexity leveraging.

A lower bound for the Boneh-Waters CPRF and Hofheinz’s construction. We then turn our attention to the bit-fixing constrained PRF by Boneh and Waters [BW13]. For this construction too, complexity leveraging—losing an exponential factor—is the only known technique to prove full security. We give strong evidence that this is inherent (even when the construction is only used as a prefix-fixing CPRF).

Concretely, we prove that every “simple” reduction (which runs the adversary once without rewinding; see Sect. 5.2) of the full security of this scheme from any decisional (and thus also search) assumption must lose an exponential factor. Our proof is a so-called meta-reduction [BV98, Cor02, FS10], showing that any reduction that breaks the underlying assumption when given access to any adversary that breaks the CPRF, could be used to break the underlying assumption without the help of an adversary.

⁵ This guessing is somewhat reminiscent of a proof technique from [HW09].

This impossibility result is similar to existing results, the closest one being a result of Lewko and Waters [LW14] ruling out security proofs without exponential loss for so-called “prefix-encryption” schemes (which satisfy some special properties). Other related results are those of Coron [Cor02] and Hofheinz et al. [HJK12], which show that security reductions for certain signature schemes must lose a factor polynomial in the number of signing queries.

The above impossibility proofs are for public-key objects, where a public key that uniquely determines the input/output distribution of the object. This property is crucially used in the proof, wherein one first gets the public key and then runs the reduction, rewinding the reduction multiple times to the point right after the public key has been received.

As we consider a secret-key primitive, the above approach seems inapplicable. We overcome this by observing that for the Boneh-Waters CPRF we can initially make some fixed “fingerprint” queries, which then uniquely determine the remaining outputs. We can therefore use the responses to these fingerprint queries instead of a public key as in [LW14].

Hofheinz [Hof14] has (independently and concurrently with us) investigated the adaptive security of bit-fixing constrained PRFs. He gives a new construction of such PRFs which is more sophisticated than the Boneh-Waters construction, and for which he can give a security reduction that only loses a polynomial factor. The main tool that allows Hofheinz to overcome our impossibility result is the use of a random oracle $H(\cdot)$. Very informally, instead of evaluating the PRF on an input X , it is evaluated on $H(X)$ which forces an attacker to make every query X explicit. Unfortunately, this idea does not work directly as it destroys the structure of the preimages, and thus makes the construction of short delegatable keys impossible. Hofheinz deals with this problem using several other ideas.

2 Preliminaries

For $a \in \mathbb{N}$, we let $[a] := \{1, 2, \dots, a\}$ and $[a]_0 := \{0, 1, \dots, a\}$. By $\{0, 1\}^{\leq a} = \bigcup_{i \leq a} \{0, 1\}^i$ we denote the set of bitstrings of length at most a , including the empty string \emptyset . By U_a we denote the random variable with uniform distribution over $\{0, 1\}^a$. We denote sampling s uniformly from a set \mathcal{S} by $s \leftarrow^* \mathcal{S}$. We let $x||y$ denote the concatenation of the bitstrings x and y . For sets \mathcal{X}, \mathcal{Y} , we denote by $\mathcal{F}[\mathcal{X}, \mathcal{Y}]$ the set of all functions $\mathcal{X} \rightarrow \mathcal{Y}$; moreover, $\mathcal{F}[a, b]$ is short for $\mathcal{F}[\{0, 1\}^a, \{0, 1\}^b]$. For $x \in \{0, 1\}^*$, we denote by x_i the i -th bit of x , and by $x[i \dots j]$ the substring $x_i||x_{i+1}||\dots||x_j$.

Definition 1 (Indistinguishability). *Two distributions X and Y are (ϵ, s) -indistinguishable, denoted $X \sim_{(\epsilon, s)} Y$, if no circuit D of size at most s can distinguish them with advantage greater than ϵ , i.e.,*

$$X \sim_{(\epsilon, s)} Y \iff \forall D, |D| \leq s : |\Pr[D(X) = 1] - \Pr[D(Y) = 1]| \leq \epsilon .$$

$X \sim_\delta Y$ denotes that the statistical distance of X and Y is δ (i.e., $X \sim_{(\delta, \infty)} Y$), and $X \sim Y$ denotes that they have the same distribution.

Definition 2 (PRG). An efficient function $G: \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda}$ is an (ϵ, s) -secure (length-doubling) **pseudorandom generator (PRG)** if

$$G(U_\lambda) \sim_{(\epsilon, s)} U_{2\lambda} .$$

Definition 3 (PRF). A keyed function $F: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y}$ is an (ϵ, s, q) -secure **pseudorandom function** if for all adversaries A of size at most s making at most q oracle queries

$$\left| \Pr_{K \leftarrow \mathcal{K}}[A^{F(K, \cdot)} \rightarrow 1] - \Pr_{f \leftarrow \mathcal{F}[\mathcal{X}, \mathcal{Y}]}[A^{f(\cdot)} \rightarrow 1] \right| \leq \epsilon .$$

Constrained pseudorandom functions. Following [BW13], we say that a function $F: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y}$ is a *constrained PRF* for a set system $\mathcal{S} \subseteq 2^\mathcal{X}$, if there is a *constrained-key space* \mathcal{K}_c and algorithms

$$F.\text{constrain}: \mathcal{K} \times \mathcal{S} \rightarrow \mathcal{K}_c \quad \text{and} \quad F.\text{eval}: \mathcal{K}_c \times \mathcal{X} \rightarrow \mathcal{Y} ,$$

which for all $k \in \mathcal{K}, S \in \mathcal{S}, x \in S$ and $k_S \leftarrow F.\text{constrain}(k, S)$ satisfy

$$F.\text{eval}(k_S, x) = \begin{cases} F(k, x) & \text{if } x \in S \\ \perp & \text{otherwise} \end{cases}$$

That is, $F.\text{constrain}(k, S)$ outputs a key k_S that allows evaluation of $F(k, \cdot)$ on all $x \in S$.

Informally, a constrained PRF F is secure, if no efficient adversary can distinguish $F(k, x^*)$ from random, even given access to $F(k, \cdot)$ and $F.\text{constrain}(k, \cdot)$ which he can query on all $x \neq x^*$ and $S \in \mathcal{S}$ where $x^* \notin S$, respectively. We will always assume that \mathcal{S} contains all singletons, i.e., $\forall x \in \mathcal{X} : \{x\} \in \mathcal{S}$; this way we do not have to explicitly give access to $F(k, \cdot)$ to an adversary, as $F(k, x)$ can be learned by querying for $k_x \leftarrow F.\text{constrain}(k, \{x\})$ and computing $F.\text{eval}(k_x, x)$.

We distinguish between selective and full security. In the selective security game the adversary must choose the challenge x^* before querying the oracles. Both games are parametrized by the maximum number q of queries the adversary makes, of which the last query is the challenge query.

$\mathbf{Exp}_{\text{CPRF}}^{\text{sel}}(A, F, b, q)$ $K \leftarrow \mathcal{K}, \hat{S} := \emptyset, c := 0$ $x^* \leftarrow A$ $A^{\mathcal{O}(\cdot)}$ $C_0 \leftarrow \mathcal{Y}, C_1 := F(K, x^*)$ A gets C_b $\tilde{b} \leftarrow A$ if $x^* \in \hat{S}$, return 0 return \tilde{b}	$\mathbf{Exp}_{\text{CPRF}}^{\text{full}}(A, F, b, q)$ $K \leftarrow \mathcal{K}, \hat{S} := \emptyset, c := 0$ $A^{\mathcal{O}(\cdot)}$ $x^* \leftarrow A$ $C_0 \leftarrow \mathcal{Y}, C_1 := F(K, x^*)$ A gets C_b $\tilde{b} \leftarrow A$ if $x^* \in \hat{S}$, return 0 return \tilde{b}	$\mathbf{Oracle } \mathcal{O}(S)$ if $c = q - 1$, return \perp $c := c + 1$ $\hat{S} := \hat{S} \cup S$ $k_S \leftarrow F.\text{constrain}(K, S)$ return k_S
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For $\text{atk} \in \{\text{sel}, \text{full}\}$ we define A 's advantage as

$$\text{Adv}_F^{\text{atk}}(A, q) = 2 \left| \Pr_{b \leftarrow \{0, 1\}}[\mathbf{Exp}_{\text{CPRF}}^{\text{atk}}(A, F, b, q) = b] - \frac{1}{2} \right| \quad (1)$$

and denote with

$$\text{Adv}_{\mathbb{F}}^{\text{atk}}(s, q) = \max_{\mathbf{A}, |\mathbf{A}| \leq s} \text{Adv}_{\mathbb{F}}^{\text{atk}}(\mathbf{A}, q)$$

the advantage of the best q -query adversary of size at most s .

Definition 4 (Security of CPRFs). *A constrained PRF \mathbb{F} is*

- **selectively** (ϵ, s, q) -**secure** if $\text{Adv}_{\mathbb{F}}^{\text{sel}}(s, q) \leq \epsilon$ and
- **fully** (ϵ, s, q) -**secure** if $\text{Adv}_{\mathbb{F}}^{\text{full}}(s, q) \leq \epsilon$.

Remark 1 (CCA1 vs. CCA2 security). In the selective and full security notion, we assume that the challenge query x^* is only made at the very end, when \mathbf{A} has no longer access to the oracle (this is reminiscent of CCA1 security). All our positive results hold for stronger notions (reminiscent to CCA2 security) where \mathbf{A} still has access to $\mathcal{O}(\cdot)$ after making the challenge query, but may not query on any S where $x^* \in S$.

Remark 2 (Multiple challenge queries). We only allow the adversary one challenge query. As observed in [BW13], this implies security against any $t > 1$ challenge queries, losing a factor of t in the distinguishing advantage, by a standard hybrid argument.

Using what is sometimes called “complexity leveraging”, one can show that selective security implies full security: given an adversary \mathbf{A} against full security, we construct a selective adversary \mathbf{B} , which at the beginning *guesses* the challenge x^* , which it outputs, then runs the \mathbf{A} and aborts if the challenge \mathbf{A} eventually outputs is different from x^* . The distinguishing advantage drops thus by a factor of the domain size $|\mathcal{X}|$. We prove the following in the full version [FKPR14].

Lemma 1 (Complexity leveraging). *If a constrained PRF $\mathbb{F}: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y}$ is (ϵ, s, q) -selectively secure, then it is $(\epsilon|\mathcal{X}|, s', q)$ -fully secure (where $s' = s - O(\log |\mathcal{X}|)$), i.e.,*

$$\text{Adv}_{\mathbb{F}}^{\text{full}}(s', q) \leq |\mathcal{X}| \cdot \text{Adv}_{\mathbb{F}}^{\text{sel}}(s, q) .$$

3 The GGM Construction

The GGM construction, named after its inventors Goldreich, Goldwasser and Micali [GGM86], is a keyed function $\text{GGM}^{\mathbb{G}}: \{0, 1\}^{\lambda} \times \{0, 1\}^* \rightarrow \{0, 1\}^{\lambda}$ from any length-doubling PRG $\mathbb{G}: \{0, 1\}^{\lambda} \rightarrow \{0, 1\}^{2\lambda}$, recursively defined as

$$\text{GGM}(K_{\emptyset}, x) = K_x \quad , \quad \text{where} \quad \forall z \in \{0, 1\}^{\leq N-1} : K_{z\|0} \| K_{z\|1} = \mathbb{G}(K_z) \quad (2)$$

(cf. Fig. 1). In [GGM86] it is shown that when the inputs are restricted to $\{0, 1\}^N$ then $\text{GGM}^{\mathbb{G}}$ is a secure PRF if \mathbb{G} is a secure PRG. Their proof is one of the first applications of the so-called hybrid argument.⁶ The proof loses a factor of $q \cdot N$ in distinguishing advantage, where q is the number of queries. We provide it in the full version [FKPR14].

⁶ The first application is in the “probabilistic encryption” paper [GM84].

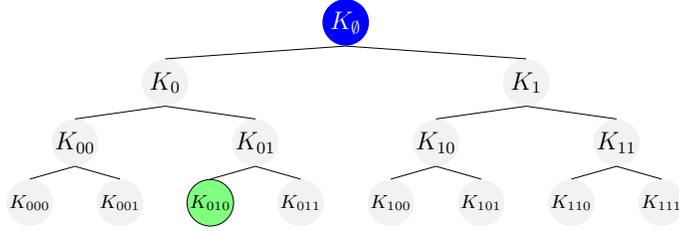


Fig. 1. Illustration of the GGM PRF. Every left child $K_{z\|0}$ of a node K_z is defined as the first half of $G(K_z)$, the right child $K_{z\|1}$ as the second half. The circled node corresponds to $GGM(K_\emptyset, 010)$.

Proposition 1 (GGM is a PRF [GGM86]). *If $G: \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda}$ is an (ϵ_G, s_G) -secure PRG then (for any N, q) $GGM^G: \{0, 1\}^\lambda \times \{0, 1\}^N \rightarrow \{0, 1\}^\lambda$ is an (ϵ, s, q) -secure PRF with*

$$\epsilon = \epsilon_G \cdot q \cdot N \quad \text{and} \quad s = s_G - O(q \cdot N \cdot |G|) .$$

3.1 GGM is a Constrained PRF

As observed recently by three works independently [BW13, BGI14, KPTZ13], the GGM construction can be used as a constrained PRF for the set \mathcal{S}_{pre} defined as

$$\mathcal{S}_{\text{pre}} = \{S_p : p \in \{0, 1\}^{\leq N}\} , \quad \text{where} \quad S_p = \{p\|z : z \in \{0, 1\}^{N-|p|}\} .$$

Thus, given a key K_p for the set S_p , one can evaluate $GGM^G(K, \cdot)$ on all inputs with prefix p . Formally, the constrained PRF with key $K = K_\emptyset$ is defined using (2) as follows:

$$\begin{aligned} GGM^G.\text{constrain}(K_\emptyset, p) &= GGM^G(K_\emptyset, p) = K_p \\ GGM^G.\text{eval}(K_p, x = p\|z) &= GGM^G(K_p, z) = K_x \end{aligned}$$

Remark 3. When the domain is defined as $\mathcal{X} := \{0, 1\}^*$ as for eq. (2) then the GGM construction is a secure *prefix-free* PRF, which means that none of the adversary's queries can be a prefix of another query (see [FKPR14]). One might be tempted to think that this fact together with the fact that constrained-key derivation is simply the GGM function itself, already implies that it is a secure constrained PRF. Unfortunately, this is not sufficient, as the (selective and full) security notions for CPRFs do allow queries that are prefixes of previous queries.

The *selective* security of this construction can be proven using a standard hybrid argument, losing only a factor of $2N$ in the distinguishing advantage. Proving full security seems much more challenging, and prior to our work it was only achieved by complexity leveraging (see Lemma 1), which loses an additional exponential factor 2^N in the distinguishing advantage, as stated in Proposition 2 below.

Remark 4. In the proof of Proposition 2 and Theorem 1 we will slightly cheat, as in the security game when $b = 0$ (i.e., when the challenge output is random) we not only replace the challenge output K_{x^*} , but also its sibling $K_{x^*[1\dots N-1]\bar{x}_N}$, with a random value. Thus, technically this only proves security for inputs of length $N - 1$ (as we can e.g. simply forbid queries $x||0, x \in \{0, 1\}^{N-1}$, in which case it is irrelevant what the sibling is, as it will never be revealed). The proofs without this cheat require one extra hybrid, which requires a somewhat different treatment than all others hybrids and thus would complicate certain proofs and definitions. Hence, we chose to not include it. The bounds stated in Proposition 2 and Theorem 1 are the bounds we get *without* this cheat.

Proposition 2. *If $G: \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda}$ is an (ϵ_G, s_G) -secure PRG then (for any N, q) $\text{GGM}^G: \{0, 1\}^N \rightarrow \{0, 1\}^\lambda$ is a constrained PRF for \mathcal{S}_{pre} which is*

1. **selectively** (ϵ, s, q) -secure, with

$$\epsilon = \epsilon_G \cdot 2N \quad \text{and} \quad s = s_G - O(q \cdot N \cdot |G|) ;$$

2. **fully** (ϵ, s, q) -secure, with

$$\epsilon = \epsilon_G \cdot 2^N 2N \quad \text{and} \quad s = s_G - O(q \cdot N \cdot |G|) .$$

Full security as stated in Item 2. of the proposition follows from selective security (Item 1.) by complexity leveraging as explained in Lemma 1. To prove selective security, we let H_0 be the real game for selective security and let H_{2N-1} be the random game, that is, where K_{x^*} is random. We then define intermediate hybrid games H_1, \dots, H_{2N-2} by embedding random values along the path to K_{x^*} . In particular, in hybrid H_i , for $1 \leq i \leq N$, the nodes $K_\emptyset, K_{x_1^*}, \dots, K_{x^*[1\dots i]}$ are random and for $N + 1 \leq i \leq 2N - 1$ the nodes $K_\emptyset, K_{x_1^*}, \dots, K_{x^*[1\dots 2N-1-i]}$ and K_{x^*} are random. Thus two consecutive games H_i, H_{i+1} differ in one node that is real in one game and random in the other, and moreover the parent of that node is random, meaning we can embed a PRG challenge. From any distinguisher for two consecutive games we thus get a distinguisher for the PRG G with the same advantage. (A formal proof can be found in [FKPR14].)

This hybrid argument only loses a factor $2N$ in distinguishing advantage, but complexity leveraging loses a huge factor 2^N . In the next section we show how to prove full security avoiding such an exponential loss.

4 Full Security with Quasipolynomial Loss

Theorem 1. *If $G: \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda}$ is an (ϵ_G, s_G) -secure PRG then (for any N, q) $\text{GGM}^G: \{0, 1\}^N \rightarrow \{0, 1\}^\lambda$ is a **fully** (ϵ, s, q) -secure constrained PRF for \mathcal{S}_{pre} , where*

$$\epsilon = \epsilon_G \cdot (3q)^{\log N} \quad \text{and} \quad s = s_G - O(q \cdot N \cdot |G|) .$$

At the end of this section we will sketch how to combine the proof of this theorem with the standard complexity leveraging proof from Proposition 2 to get a smaller loss of $\epsilon = \epsilon_G \cdot 2q \log q \cdot (3q)^{\log N - \log \log q}$.

Proof idea. We can view the real and the random game for CPRF security as having distance N , in the sense that from the only node in which they differ (which is the challenge node K_{x^*}) we have to walk up N nodes until we reach a node that was chosen uniformly at random (which here is the root K_\emptyset).

As outlined in Sect. 1.1, our goal is to halve that distance. For this, we could define two intermediate hybrids which are defined as the real and the random games, except that the node half way down the path to x^* , i.e., $K_{x^*[1\dots N/2]}$, is a random node. This is illustrated in Fig. 2, where a row depicts the path from the root, labeled ‘0’, to x^* , labeled ‘8’ and where dark nodes correspond to random values. The path at the top of the figure is the real and the one at the bottom is the random game (ignore anything in the boxes for now), and the intermediate hybrids are the 2nd and the 3rd path. Of these 4 hybrids, each pair of consecutive hybrids has the following property: they differ in one node and its distance to the closest random node above is $N/2$.

There is a problem with this approach because the intermediate hybrid games we have just constructed are not even well-defined, as the value $x^*[1\dots N/2]$ is only known when the adversary makes his challenge query. This is also the case for x^* itself, but K_{x^*} only needs to be computed once x^* is queried; in contrast, $K_{x^*[1\dots N/2]}$ could have been computed earlier in the game, if the value of some constrained-key query is a descendant of it. In order to avoid possible inconsistencies, we do the following: we guess which of the adversary’s queries will be the first one with a prefix $x^*[1\dots N/2]$. As there are at most q queries and there always exists a query with this property (at latest the challenge query itself), the probability of guessing correctly is $1/q$. If we guess correctly then the node $x^*[1\dots N/2]$ is known precisely when the value $K_{x^*[1\dots N/2]}$ is computed for the first time and we can correctly simulate the game. If our guess was wrong, we abort.

Assuming an attacker can distinguish between the real and the random game, there must be two consecutive hybrids of the 4 hybrids that it can distinguish with at least one third of his original advantage. Between these two hybrids, which differ in one node d , we can again embed two intermediate hybrids, which have a random value half way between d and the closest random node above (cf. the outer box in Fig. 2). We continue to do so until we reach two hybrids where there is a random node immediately above the differing node. A distinguisher between two such games can then be used to break the PRG.

Neighboring sets with low weight. Before starting with the proof, we introduce some notation. It will be convenient to work with ternary numbers, which we represent as strings of digits from $\{0, 1, 2\}$ within angular brackets $\langle \dots \rangle$. We denote repetition of digits as $0_n = 0\dots 0$ (n times). Addition will also be in ternary, e.g., $\langle 202 \rangle + \langle 1 \rangle = \langle 210 \rangle$.

Let $N = 2^n$ be a power of 2. In the proof of Theorem 1 we will construct $3^n + 1$ subsets $\mathcal{S}_{\langle 0 \rangle}, \dots, \mathcal{S}_{\langle 10_n \rangle} \subset \{0, \dots, N\}$. These sets will define the positions in the path to the challenge where we make random guesses in a particular hybrid. The following definition measures how “close” sets (that differ in one element) are and will be useful in defining neighboring hybrids.

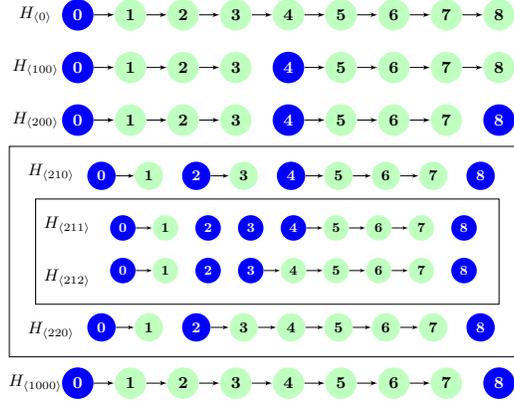


Fig. 2. Concrete example ($n = 3$) illustrating the iterative construction of hybrids in Theorem 1.

Definition 5 (Neighboring sets). For $k \in \mathbb{N}^+$, sets $\mathcal{S}, \mathcal{S}' \subset \mathbb{N}^0$, $\mathcal{S} \neq \mathcal{S}'$ are k -neighboring if

1. $\mathcal{S} \Delta \mathcal{S}' := (\mathcal{S} \cup \mathcal{S}') \setminus (\mathcal{S} \cap \mathcal{S}') = \{d\}$ for some $d \in \mathbb{N}^0$, i.e., they differ in exactly one element d .
2. $d - k \in \mathcal{S}$.
3. $\forall i \in [k - 1]: d - i \notin \mathcal{S}$.

We define the first set (with index $0 = \langle 0 \rangle$) and the and last set (with index $3^n = \langle 10_n \rangle$) as

$$\mathcal{S}_{\langle 0 \rangle} := \{0\} \quad \text{and} \quad \mathcal{S}_{\langle 10_n \rangle} := \{0, N\} . \quad (3)$$

(They will correspond to the real game, where only the root at depth ‘0’ is random, and the random game, where the value for x^* at depth N is random too.) The remaining intermediate sets are defined recursively as follows. For $\ell = 0, \dots, n$, we define the ℓ -th level of sets to be all the sets of the form $\mathcal{S}_{\langle ?0_{n-\ell} \rangle}$ (i.e., whose index in ternary ends with $(n - \ell)$ zeros). Thus, $\mathcal{S}_{\langle 0 \rangle}$ and $\mathcal{S}_{\langle 10_n \rangle}$ are the (only) level-0 sets.

Let $\mathcal{S}_I, \mathcal{S}_{I'}$ be two consecutive level- ℓ sets, by which we mean that $I' = I + \langle 10_{n-\ell} \rangle$. By construction, these sets will differ in exactly one element $\{d\}$ (i.e., $\mathcal{S}_I \neq \mathcal{S}_{I'}$; and $\mathcal{S}_I \cup \{d\} = \mathcal{S}_{I'}$ or $\mathcal{S}_{I'} \cup \{d\} = \mathcal{S}_I$). Then the two level- $(\ell + 1)$ sets between the level- ℓ sets $\mathcal{S}_I, \mathcal{S}_{I'}$ are defined as

$$\mathcal{S}_{I+\langle 10_{n-(\ell+1)} \rangle} := \mathcal{S}_I \cup \{d - \frac{N}{2^{\ell+1}}\} \quad \text{and} \quad \mathcal{S}_{I'-\langle 10_{n-(\ell+1)} \rangle} := \mathcal{S}_{I'} \cup \{d - \frac{N}{2^{\ell+1}}\} . \quad (4)$$

A concrete example for $N = 2^n = 2^3 = 8$ is illustrated in Fig. 2 (where the dark nodes of H_I correspond to \mathcal{S}_I).

An important fact we will use is that consecutive level- ℓ sets are $(N/2^\ell)$ -neighboring (see Definition 5); in particular, consecutive level- n sets (the 4 lines

in the box in Fig. 2 illustrate 4 consecutive sets) are thus 1-neighboring, i.e.,

$$\forall I \in \{\langle 0 \rangle, \dots, \langle 2n \rangle\} : \mathcal{S}_I \Delta \mathcal{S}_{I+\langle 1 \rangle} = \{d\} \quad \text{and} \quad d-1 \in \mathcal{S}_I . \quad (5)$$

Proof of Theorem 1. Below we prove two lemmata (2 and 3) concerning the games defined in Fig. 3, from which the theorem follows quite immediately. As the games and the lemmata are rather technical, we first intuitively explain what is going on, going through a concrete example as illustrated in Fig. 2.

To prove the theorem, we assume that there exists an adversary A_f that breaks the *full* security of GGM^G with some advantage ϵ , and from this, we want to construct a distinguisher for G with advantage at least $\epsilon/(3q)^n$, where $n = \log N$. Like in the proof of Proposition 2, we can think of the two games that A_f distinguishes as the games where we let A_f query GGM^G , but along the path from the root K_\emptyset down to the challenge K_{x^*} the nodes are either computed by G or they are random values. The position of the random values are defined by the set $\mathcal{S}_{\langle 0 \rangle} = \{0\}$ for the real game and by $\mathcal{S}_{\langle 10_n \rangle} = \{0, N\}$ for the random game: in both cases the root K_\emptyset is random, and in the latter game the final output K_{x^*} is also random. We call these two games $H_{\langle 0 \rangle}^\emptyset$ and $H_{\langle 10_n \rangle}^\emptyset$, and they correspond to the games defined in Fig. 3 with $\mathcal{P} = \emptyset$, and $I = \langle 0 \rangle$ and $\langle 10_n \rangle$, respectively). As just explained, they satisfy

$$H_{\langle 0 \rangle}^\emptyset \sim \text{Exp}_{\text{CPRF}}^{\text{full}}(A_f, \text{GGM}^G, 0, q) \quad \text{and} \quad H_{\langle 10_n \rangle}^\emptyset \sim \text{Exp}_{\text{CPRF}}^{\text{full}}(A_f, \text{GGM}^G, 1, q) .$$

Thus, if A_f breaks the full security of GGM^G with advantage ϵ then

$$|\Pr[H_{\langle 0 \rangle}^\emptyset = 1] - \Pr[H_{\langle 10_n \rangle}^\emptyset = 1]| \geq \epsilon . \quad (6)$$

In the proof of Proposition 2 we were able to “connect” the real and random experiments H_0 and H_{2N-1} via intermediate hybrids H_1, \dots, H_{2N-2} , such that from a distinguisher for any two consecutive hybrids we can build a distinguisher for G with the same advantage.

We did this by using random values (instead of applying G) in some steps along the path from the root K_\emptyset to the challenge K_{x^*} . Here we cannot use the same approach to connect $H_{\langle 0 \rangle}^\emptyset$ and $H_{\langle 10_n \rangle}^\emptyset$, as these games consider full (and not selective) security, where we learn x^* only at the very end, and thus “the path to x^* ” is not even defined until the adversary makes the challenge query.

We could of course reduce the problem from the full to the selective setting by guessing x^* at the beginning like in the proof of Lemma 1, but this would lose a factor 2^N , which is what we want to avoid.

Instead of guessing the entire x^* , we will guess something easier. During the experiment $H_{\langle 0 \rangle}$ we have to compute at most q children $K_{z\|0} \| K_{z\|1} = G(K_z)$ of nodes at level $N/2 - 1$, i.e., $z \in \{0, 1\}^{N/2-1}$. One of these K_z satisfies $z = x^*[1 \dots N/2 - 1]$, that is, it lies on the path from the root K_\emptyset to the challenge K_{x^*} (potentially this happens only at the very last query $x_q = x^*$). We randomly guess $q_{N/2} \stackrel{*}{\leftarrow} [q]$ for which invocation of G this will be the case *for the first time*. Note that we have to wait until A_f makes its last query $x_q = x^*$ before we know

<pre> Experiment $H_I^{\mathcal{P}}$ // $I \in \{(0), \dots, \langle 10_n \rangle\}$ // $\mathcal{P} = \{p_1, \dots, p_t\} \subseteq [N-1]$ // $\mathcal{S}_I \subseteq \mathcal{P} \cup \{0, N\}$, // \mathcal{S}_I defined by eq. (3) and (4). $\forall x \in \{0, 1\}^{\leq N} : K_x := \perp$ $K_\emptyset \stackrel{*}{\leftarrow} \{0, 1\}^\lambda$ // Initialize counters: $\forall j = 1 \dots N-1 : c_j = 0$ // Make a random guess for each // element in $\mathcal{P} = \{p_1, \dots, p_t\}$: $\forall j \in [t] : q_{p_j} \stackrel{*}{\leftarrow} [q]$ // A_f can make exactly q distinct // oracle queries x_1, \dots, x_q; // the last (challenge) query // $x_q = x^*$ must be in $\{0, 1\}^N$: $A_f^{\mathcal{O}(\cdot)}$ $\tilde{b} \leftarrow A_f$ // Only if guesses q_{p_1}, \dots, q_{p_t} // were correct, return \tilde{b}, // otherwise return 0: if $\forall p \in \mathcal{P} : x^*[1 \dots p-1] = z_{p-1}$ then return \tilde{b} else return 0 fi </pre>	<pre> $\mathcal{O}(x = x[1 \dots \ell])$ // Return K_x if it is already defined: if $K_x \neq \perp$ then return K_x fi // Get parent of K_x recursively: $K_{x[1 \dots \ell-1]} := \mathcal{O}(x[1 \dots \ell-1])$ // Increase counter for level $\ell-1$: $c_{\ell-1} = c_{\ell-1} + 1$ // Compute K_x and its sibling using G, // unless its parent $K_{x[1 \dots \ell-1]}$ is a node // which we guessed will be on the path // from K_\emptyset and K_{x^*} and as $\ell \in \mathcal{P}$ we // must use a random value at this level; // OR this is the challenge query $x_q = x^*$ // and $N \in \mathcal{S}_I$, which means the answer // to the challenge is random: if ($\ell \in \mathcal{P}$ and $c_{\ell-1} = q_{\ell-1}$) OR ($x = x_q$ and $N \in \mathcal{S}_I$) $K_{x[1 \dots \ell-1] 0} K_{x[1 \dots \ell-1] 1} \stackrel{*}{\leftarrow} U_{2\lambda}$ // Store this node to check if guess // was correct later: $z_{\ell-1} = x[1 \dots \ell-1]$ else $K_{x[1 \dots \ell-1] 0} K_{x[1 \dots \ell-1] 1} := G(K_{x[1 \dots \ell-1]})$ fi return K_x </pre>
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Fig. 3. Definition of the hybrid games from the proof of Theorem 1. The sets \mathcal{S}_I are as in Equations (3) and (4). The hybrid $H_I^{\mathcal{P}}$ is defined like the full security game of a q -query adversary A_f against the CPRF GGM^G , but where we “guess”, for any value $p \in \mathcal{P}$, at which point in the experiment the node at depth p on the path from the root K_\emptyset to the challenge K_{x^*} is computed. (Concretely, the guess is that it’s the c_{p-1} -th time we compute the children of a node at level $p-1$, we define the p level node $K_{x^*[1 \dots \ell]}$ on the path.) At a subset of these points, namely \mathcal{S}_I , we embed random values. The final output is 0 unless all guesses were correct, in which case we forward A_f ’s output.

whether our guess was correct. If the guess was wrong, we output 0; otherwise we output A_f ’s output. We will denote the position of the node down to which our guessed query should equal the path to x^* as superscript of the hybrid H . The experiment just described corresponds thus to hybrid $H_{(0)}^{\{N/2\}}$, as defined in Fig. 3.

The games $H_{(0)}^{\{N/2\}}$ and $H_{(10_n)}^{\{N/2\}}$ behave *exactly* like $H_{(0)}^\emptyset$ and $H_{(10_n)}^\emptyset$, except for the final output, which in the former two hybrids is set to 0 with probability $1 - 1/q$, and left unchanged otherwise (namely, if our random guess $q_{N/2} \stackrel{*}{\leftarrow} [q]$ turns out to be correct, which we know after learning x^*). This implies

$$\Pr[H_{(0)}^{\{N/2\}} = 1] = \Pr[H_{(0)}^\emptyset = 1] \cdot \frac{1}{q} \quad \text{and} \quad \Pr[H_{(10_n)}^{\{N/2\}} = 1] = \Pr[H_{(10_n)}^\emptyset = 1] \cdot \frac{1}{q} ,$$

and with (6)

$$|\Pr[H_{(0)}^{\{N/2\}} = 1] - \Pr[H_{(10_n)}^{\{N/2\}} = 1]| \geq \epsilon/q . \quad (7)$$

What did we gain? We paid a factor q in the advantage for aborting when our guess $q_{N/2}$ was wrong. What we gained is that when we guess correctly we know $x^*[1 \dots N/2]$, i.e., the node half way in between the root and the challenge.

We use this fact to define two new hybrids $H_{(10_{n-1})}^{\{N/2\}}, H_{(20_{n-1})}^{\{N/2\}}$ which are defined like $H_{(0)}^{\{N/2\}}, H_{(10_n)}^{\{N/2\}}$, respectively, but where the children of $K_{x^*[1 \dots N/2-1]}$ are uniformly random instead of being computed by applying G to $K_{x^*[1 \dots N/2-1]}$.

Fig. 2 (ignoring the boxes for now) illustrates the path from K_\emptyset to K_{x^*} in the hybrids $H_{(0)}^{\{4\}}, H_{(100)}^{\{4\}}, H_{(200)}^{\{4\}}, H_{(1000)}^{\{4\}}$ assuming the guessing was correct (a node with label i corresponds to $K_{x^*[1 \dots i]}$, dark nodes are sampled at random, and green ones by applying G to the parent).

By (7) we can distinguish the first from the last hybrid with advantage ϵ/q , and thus there are two consecutive hybrids in the sequence $H_{(0)}^{\{N/2\}}, H_{(10_{n-1})}^{\{N/2\}}, H_{(20_{n-1})}^{\{N/2\}}, H_{(10_n)}^{\{N/2\}}$ that we can distinguish with advantage at least $\epsilon/(3q)$. For concreteness, let us fix parameters $N = 8 = 2^3 = 2^n$ as in Fig. 2 and assume that this is the case for the last two hybrids in the sequence, i.e.,

$$|\Pr[H_{(200)}^{\{4\}} = 1] - \Pr[H_{(1000)}^{\{4\}} = 1]| \geq \epsilon/(3q) . \quad (8)$$

The central observation here is that the above guessing step (losing a factor q) followed by a hybrid argument (losing a factor 3) transformed a distinguishing advantage ϵ for two hybrids $H_{(0)}^\emptyset, H_{(1000)}^\emptyset$ which have random values embedded along the path from K_\emptyset to K_{x^*} on positions defined by N -neighboring sets $\mathcal{S}_{(0)}, \mathcal{S}_{(1000)}$, into a distinguishing advantage of $\epsilon/(3q)$ for two hybrids that correspond to $N/2$ -neighboring sets, e.g. $\mathcal{S}_{(200)}$ and $\mathcal{S}_{(1000)}$.

We can now iterate this approach, in each iteration losing a factor $3q$ in distinguishing advantage, but getting hybrids that correspond to sets of half the neighboring distance. After $n = \log N$ iterations we end up with hybrids that correspond to 1-neighboring sets, and can be distinguished with advantage $\epsilon/(3q)^n$. We will make this formal in Lemma 3 below. From any distinguisher for hybrids corresponding to two 1-neighboring sets we can construct a distinguisher for G with the same advantage, as formally stated in Lemma 2 below. Let's continue illustrating the approach using the hybrids illustrated in Fig. 2.

Recall that we assumed that we can distinguish $H_{(200)}^{\{4\}}$ and $H_{(1000)}^{\{4\}}$ as stated in eq. (8). We now embed hybrids corresponding to the sets $\mathcal{S}_{(210)}, \mathcal{S}_{(220)}$ in between, illustrated in the outer box in Fig. 2 (ignore the inner box for now). Since $\mathcal{S}_{(200)} \Delta \mathcal{S}_{(1000)} = \{4\}$, by eq. (4) for $\ell = 1$, we construct $\mathcal{S}_{(200)+(10)} = \mathcal{S}_{(200)} \cup \{4 - \frac{8}{2^2} = 2\}$ and $\mathcal{S}_{(1000)-(10)} = \mathcal{S}_{(1000)} \cup \{2\}$. We add this new element $\{2\}$ to the "guessing set" $\{4\}$, at the price of losing a factor q in distinguishing advantage compared to eq. (8):

$$|\Pr[H_{(200)}^{\{2,4\}} = 1] - \Pr[H_{(1000)}^{\{2,4\}} = 1]| \geq \epsilon/(3q^2) . \quad (9)$$

We can now consider the sequence of hybrids $H_{\langle 200 \rangle}^{\{2,4\}}, H_{\langle 210 \rangle}^{\{2,4\}}, H_{\langle 220 \rangle}^{\{2,4\}}, H_{\langle 1000 \rangle}^{\{2,4\}}$. There must be two consecutive hybrids that can be distinguished with advantage $\epsilon/(3^2q^2)$. Let's assume this is the case for the middle two.

$$|\Pr[H_{\langle 210 \rangle}^{\{2,4\}} = 1] - \Pr[H_{\langle 220 \rangle}^{\{2,4\}} = 1]| \geq \epsilon/(3^2q^2) . \quad (10)$$

Now $\mathcal{S}_{\langle 210 \rangle} \Delta \mathcal{S}_{\langle 220 \rangle} = \{4\}$, and $4 - 8/2^3 = 3$, so we add $\{3\}$ to the guessing set losing another factor q :

$$|\Pr[H_{\langle 210 \rangle}^{\{2,3,4\}} = 1] - \Pr[H_{\langle 220 \rangle}^{\{2,3,4\}} = 1]| \geq \epsilon/(3^2q^3) , \quad (11)$$

and can now consider the games $H_{\langle 210 \rangle}^{\{2,3,4\}}, H_{\langle 211 \rangle}^{\{2,3,4\}}, H_{\langle 212 \rangle}^{\{2,3,4\}}, H_{\langle 220 \rangle}^{\{2,3,4\}}$ as shown inside the two boxes in Fig. 2. Two consecutive hybrids in this sequence must be distinguishable with advantage at least $1/3$ of the advantage we had for the first and last hybrid in this sequence; let's assume this is the case for the last two, then:

$$|\Pr[H_{\langle 212 \rangle}^{\{2,3,4\}} = 1] - \Pr[H_{\langle 220 \rangle}^{\{2,3,4\}} = 1]| \geq \epsilon/(3^3q^3) . \quad (12)$$

We have thus shown the existence of two games $H_I^{\mathcal{P}}$ and $H_{I+\langle 1 \rangle}^{\mathcal{P}}$ (what \mathcal{P} and I are exactly is irrelevant for the rest of the argument) that can be distinguished with advantage $\epsilon/(3q)^n$. Any two consecutive (i.e., 1-neighboring) hybrids have the following properties (cf. eq. 5). They only differ in one node on the path to x^* and its parent node is random. Moreover, the position of the differing node is in the guessing set \mathcal{P} , meaning we know its position in the tree. Together, this means we can use a distinguisher between $H_I^{\mathcal{P}}$ and $H_{I+\langle 1 \rangle}^{\mathcal{P}}$ to break \mathbf{G} : Given a challenge for \mathbf{G} we embed it as the value of the differing node and, depending whether it was real or random, simulate one hybrid or the other. We formalize this in the following lemma, which is proven in the full version [FKPR14].

Lemma 2. *For any $I \in \{\langle 0 \rangle, \dots, \langle 2_n \rangle\}$, $\mathcal{P} \subset \{1, \dots, N-1\}$ where $\mathcal{S}_I \cup \mathcal{S}_{I+\langle 1 \rangle} \subseteq \mathcal{P} \cup \{0, N\}$ (so the games $H_{I+\langle 1 \rangle}^{\mathcal{P}}, H_I^{\mathcal{P}}$ are defined) the following holds. If*

$$|\Pr[H_I^{\mathcal{P}} = 1] - \Pr[H_{I+\langle 1 \rangle}^{\mathcal{P}} = 1]| = \delta$$

then \mathbf{G} is not a (δ, s) -secure PRG for $s = |\mathbf{A}_{\mathbf{f}}| - O(q \cdot N \cdot |\mathbf{G}|)$.

Lemma 3. *For $\ell \in \{0, \dots, n-1\}$, any consecutive level- ℓ sets $\mathcal{S}_I, \mathcal{S}_{I'}$ (i.e., I, I' are of the form $\langle ?0_{n-\ell} \rangle$ and $I' = I + \langle 10_{n-\ell} \rangle$) and any \mathcal{P} for which the hybrids $H_I^{\mathcal{P}}, H_{I'}^{\mathcal{P}}$ are defined (which is the case if $\mathcal{S}_I \cup \mathcal{S}_{I'} \subseteq \mathcal{P} \cup \{0, N\}$), the following holds. If*

$$|\Pr[H_I^{\mathcal{P}} = 1] - \Pr[H_{I'}^{\mathcal{P}} = 1]| = \delta \quad (13)$$

then for some consecutive level- $(\ell+1)$ sets $J \in \{I, I + \langle 10_{n-\ell-1} \rangle, I + \langle 20_{n-\ell-1} \rangle\}$ and $J' = J + \langle 10_{n-\ell-1} \rangle$ and some \mathcal{P}' :

$$|\Pr[H_J^{\mathcal{P}'} = 1] - \Pr[H_{J'}^{\mathcal{P}'} = 1]| = \delta/(3q) .$$

The proof of Lemma 3 is in [FKPR14]. The theorem now follows from Lemmata 2 and 3 as follows. Assume a q -query adversary A_f breaks the full security of GGM^G for domain $\mathcal{X} = \{0, 1\}^{2^n}$ with advantage ϵ , which, as explained in the paragraph before eq. (6), means that we can distinguish the two level-0 hybrids $H_{\langle 0 \rangle}^\emptyset$ and $H_{\langle 10_n \rangle}^\emptyset$ with advantage ϵ . Applying Lemma 3 n times, we get that there exist consecutive level- n hybrids $H_I^P, H_{I+(1)}^P$ that can be distinguished with advantage $\epsilon/(3q)^n$, which by Lemma 2 implies that we can break the security of G with the same advantage $\epsilon/(3q)^n$. This concludes the proof of Theorem 1.

To reduce the loss to $2q \log q \cdot (3q)^{n - \log \log q}$ as stated below Theorem 1, we use the same proof as above, but stop after $n - \log \log q$ (instead of n) iterations. At this point, we have lost a factor $(3q)^{n - \log \log q}$, and have constructed games that are $(\log q)$ -neighboring. We can now use a proof along the lines of the proof of Proposition 2, and guess the entire remaining path of length $\log q$ at once. This step loses a factor $2q \log q$ (a factor $2^{\log q} = q$ to guess the path, and another $2 \log q$ as we have a number of hybrids which is twice the length of the path).

5 Impossibility Result for the Boneh-Waters PRF

In this section we show that we cannot hope to prove full security without an exponential loss for another constrained PRF, namely the one due to Boneh and Waters [BW13].

5.1 The Boneh-Waters Constrained PRF

Leveled κ -linear maps. The Boneh-Waters constrained PRF [BW13] is based on leveled multilinear maps [GGH13, CLT13], of which they use the following abstraction.

We assume a *group generator* \mathcal{G} that takes as input a security parameter 1^λ and the number of levels $\kappa \in \mathbb{N}$ and outputs a sequence of groups $(\mathbb{G}_1, \dots, \mathbb{G}_\kappa)$, each of prime order $p > 2^\lambda$, generated by g_i , respectively, such that there exists a set of bilinear maps $\{e_{i,j} : \mathbb{G}_i \times \mathbb{G}_j \rightarrow \mathbb{G}_{i+j} \mid i, j \geq 1; i + j \leq \kappa\}$ with

$$\forall a, b \in \mathbb{Z}_p : e_{i,j}(g_i^a, g_j^b) = (g_{i+j})^{ab} .$$

(For simplicity we will omit the indices of e .) Security of the PRF is based on the following assumption.

The κ -*multilinear decisional Diffie-Hellman assumption* states that given the output of $\mathcal{G}(1^\lambda, \kappa)$ and $(g_1, g_1^{c_1}, \dots, g_1^{c_{\kappa+1}})$ for random $(c_1, \dots, c_{\kappa+1}) \leftarrow^* \mathbb{Z}_p^{\kappa+1}$, it is hard to distinguish $(g_\kappa)^{\prod_{j \in [\kappa+1]} c_j}$ from a random element in \mathbb{G}_κ with better than negligible advantage in λ .

The Boneh-Waters bit-fixing PRF. Boneh and Waters [BW13] define a PRF with domain $\mathcal{X} = \{0, 1\}^N$ and range $\mathcal{Y} = \mathbb{G}_\kappa$, where $\kappa = N + 1$. The sets $S \subseteq \mathcal{X}$ for which constrained keys can be derived are subsets of \mathcal{X} where certain bits are fixed; a set S is described by a vector $v \in \{0, 1, ?\}^N$ (where ‘?’ acts as a wildcard) as $S_v := \{x \in \{0, 1\}^N \mid \forall i \in [N] : (v_i = ?) \vee (x_i = v_i)\}$.

The PRF is set up for domain $\mathcal{X} = \{0, 1\}^N$ by running $\mathcal{G}(1^\lambda, N + 1)$ to generate a sequence of groups $(\mathbb{G}_1, \dots, \mathbb{G}_{N+1})$. We let g denote the generator of \mathbb{G}_1 . Secret keys are random elements from $\mathcal{K} := \mathbb{Z}_p^{2N+1}$:

$$k = (\alpha, d_{1,0}, d_{1,1}, \dots, d_{N,0}, d_{N,1}) . \quad (14)$$

and the PRF is defined as

$$\mathbf{F}: \mathcal{K} \times \mathcal{X} \rightarrow \mathcal{Y} , \quad (k, x) \mapsto (g_{N+1})^{\alpha \prod_{i \in [N]} d_{i,x_i}} .$$

F.constrain(k, v): On input a key k as in (14) and $v \in \{0, 1, ?\}^N$ describing the constrained set, output the key $k_v := (v, K, \{D_{i,b}\}_{i \in [N] \setminus V, b \in \{0,1\}})$, where $V := \{i \in [N] \mid v_i \neq ?\}$ is the set of fixed indices,

$$K := (g_{|V|+1})^{\alpha \prod_{i \in V} d_{i,v_i}} \quad \text{and} \quad D_{i,b} := g^{d_{i,b}} , \quad \text{for } i \in [N] \setminus V, b \in \{0, 1\} .$$

F.eval(k_v, x): On input $k_v = (v, K, \{D_{i,b}\}_{i \in [N] \setminus V, b \in \{0,1\}})$ and $x \in \mathcal{X}$:

- if for some $i \in V$: $x_i \neq v_i$, return \perp (as x is not in S_v);
- if $|V| = N$, output K (as $S_v = \{v\}$ and $K = \mathbf{F}(k, v)$);
- else, compute $T := (g_{N-|V|})^{\prod_{i \in [N] \setminus V} d_{i,x_i}}$ via repeated application of the bilinear maps to the elements $D_{i,x_i} = g^{d_{i,x_i}}$ for $i \in [N] \setminus V$ and output $e(T, K) = (g_{N+1})^{\alpha \prod_{i \in [N]} d_{i,x_i}} = \mathbf{F}(k, x)$.

In [BW13] it is shown how to use an adversary breaking the constrained PRF for N -bit inputs with advantage $\epsilon(\lambda)$ to break the $(N + 1)$ -multilinear decisional Diffie-Hellman assumption with advantage $\frac{1}{2^N} \cdot \epsilon(\lambda)$. (The exponential factor comes from security leveraging.) In the next section we show that this is optimal in the sense that every simple reduction from a decisional problem must lose a factor that is exponential in the input length N .

We actually prove a stronger statement. First, this security loss is necessary even when the CPRF is only used as a *prefix-fixing* PRF, that is, constrained keys are only issued for sets $S_{(z,?,\dots?)}$ with $z \in \{0, 1\}^{\leq N}$. Second, the loss is necessary even when one only wants to prove *unpredictability* of the CPRF, where the adversary must *compute* $\mathbf{F}(k, x^*)$ instead of distinguishing it from random.

Definition 6 (Unpredictability). *Consider the following experiment for a constrained PRF $(\mathbf{F}, \mathbf{F.constrain}, \mathbf{F.eval})$.*

- The challenger chooses $k \xleftarrow{*} \mathcal{K}$;
- \mathbf{A} can query $\mathbf{F.constrain}$ for sets S_i ;
- \mathbf{A} wins if it outputs $(x, \mathbf{F}(k, x))$ with $x \in \mathcal{X}$ and $x \notin S_i$ for all queried S_i .

The CPRF is (ϵ, t, q) -**unpredictable** if no \mathbf{A} running in time at most t making at most q queries can win the above game with probability greater than ϵ .

Since unpredictability follows from pseudorandomness without any security loss (we assume that the domain \mathcal{X} is of superpolynomial size), our impossibility result holds a fortiori for pseudorandomness. In particular, this precludes security proofs for the Boneh-Waters CPRF using the technique from Sect. 4.

5.2 Adaptive Security of the Boneh-Waters CPRF

Hierarchical identity-based encryption (HIBE) [HL02] is a generalization of identity-based encryption where the identities are arranged in a hierarchy and from a key for an identity id one can derive keys for any identities that are below id . In the security game for HIBE the adversary receives the parameters and can query keys for any identity. He then outputs (id, m_0, m_1) and, provided that id is not below any identity for which he queried a key, receives the encryption for id of one of the two messages, and wins if he guesses which one it was.

Lewko and Waters [LW14], following earlier work [Cor02,HJK12], show that it is hard to prove full security of HIBE schemes if one can check whether secret keys and ciphertexts are correctly formed w.r.t. the public parameters. In particular, they show that a simple black-box reduction (that is, one that runs the attacker once without rewinding; see below) from a decisional assumption must lose a factor that is exponential in the depth of the hierarchy. We adapt their proof technique and show that a proof of full security of the Boneh-Waters PRF with constrained keys for prefix-fixing must lose a factor that is exponential in the length of the PRF inputs.

The proof idea in [LW14] is the following: Assume that there exists a reduction which breaks a challenge with some probability δ after interacting with an adversary that breaks the security of the HIBE with some probability ϵ . We define a concrete adversary A , which, after receiving the public parameters, guesses a random identity id at the lowest level of the hierarchy and then queries keys for all identities except id , checking whether they are consistent with the parameters. Finally it outputs a challenge query for id .

Given a challenge, we run the reduction and simulate this adversary until we have keys for all identities except id . We then rewind the reduction to the point right after it sent the parameters to A and simulate A again (choosing a fresh random identity id' ; thus $id' \neq id$ with high probability). A now asks for a challenge for id' and can break it by using the key for id' it received in the first run. It is crucial that keys can be verified w.r.t. the parameters, as this guarantees that the reduction cannot detect that a key from the first run was used to win in the second run (the parameters being the same in both runs).

The reduction can thus be used to break the challenge without any adversary, as we can simulate the adversary ourselves. (The actual proof, as well as that of Theorem 2, is more complex, as we need to rewind more than once.) We formally define decisional problems and simple reductions, following [LW14].

Definition 7. A *non-interactive decisional problem* $\Pi = (C, \mathcal{D})$ is described by a set of challenges C and a distribution \mathcal{D} on C . Each $c \in C$ is associated with a bit $b(c)$, the solution for challenge c . An algorithm A (ϵ, t) -solves Π if A runs in time at most t and $\Pr_{c \leftarrow \mathcal{D}} [b(c) \leftarrow A(c)] \geq \frac{1}{2} + \epsilon$.

Definition 8. An algorithm \mathcal{R} is a **simple** $(t, \epsilon, q, \delta, t')$ -reduction from a decisional problem Π to breaking unpredictability of a CPRF if, when given black-box access to any adversary A that (t, ϵ, q) -breaks unpredictability, \mathcal{R} (δ, t') -solves Π after simulating the unpredictability game once for A .

We show that every simple reduction from a decisional problem to unpredictability of the Boneh-Waters CPRF must lose at least a factor exponential in N . Instead of checking validity of keys computed by the reduction w.r.t. the public parameters, as in [LW14], we show that after two concrete key queries, the secret key k used by the reduction is basically fixed; the two received constrained keys are thus a “fingerprint” of the secret key. Moreover, we show that, by using the multilinear map, correctness of any key can be verified w.r.t. to this fingerprint; which gives us the required checkability property. We define an adversary A that we can simulate by rewinding the reduction: After making the fingerprint queries, A chooses a random value $x^* \in \mathcal{X}$ and queries keys which allow it to evaluate all other domain points, checking every key is consistent with the fingerprint. (Note that keys for $(1 - x_1^*, ?, \dots)$, $(x_1^*, 1 - x_2^*, ?, \dots)$, $\dots, (x_1^*, \dots, x_{N-1}^*, 1 - x_N^*)$ allow evaluation of the PRF on $\mathcal{X} \setminus \{x^*\}$.)

By rewinding the reduction to the point after receiving the fingerprint and choosing a different x' , we can break security by using one of the keys obtained in the first run to evaluate the function at x' . In [FKPR14] we prove the following.

Theorem 2. *Let $\Pi(\lambda)$ be a decisional problem for which no algorithm running in time $t = \text{poly}(\lambda)$ has an advantage non-negligible in λ . Let \mathcal{R} be a simple $(t, \epsilon, q, \delta, t')$ reduction from Π to unpredictability of the Boneh-Waters prefix-constrained PRF with domain $\{0, 1\}^N$, with $t, t' = \text{poly}(\lambda)$, and $q \geq N - 1$. Then δ vanishes exponentially as a function of N (up to terms that are negligible in λ).*

The reason why our impossibility result does not apply to the GGM construction is that its constrained keys are not “checkable”. This is why in the intermediate hybrids we can embed random nodes on the path to x^* , which lead to constrained keys that are not correctly computed.

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